

# Neutrosophic Systems with Applications, Vol. 12, 2023



# An Efficient Optimal Solution Method for Neutrosophic Transport Models: Analysis, Improvements, and Examples

Maissam Jdid 1,\* D and Florentin Smarandache 2 D

- <sup>1</sup> Faculty member, Damascus University, Faculty of Science, Department of Mathematics, Syria; maissam.jdid66@damascusuniversity.edu.sy.
- University of New Mexico, Mathematics, Physics, and Natural Sciences Division 705 Gurley Ave., Gallup, NM 87301, USA; smarand@unm.edu.
  - \* Correspondence: maissam.jdid66@damascusuniversity.edu.sy.

**Abstract:** Transport issues aim to determine the number of units that will be transferred from the production centers to consumption areas so that the cost of transportation is as low as possible, taking into account the conditions of supply and demand. Due to the great importance of these issues and to obtain more accurate results that take into account all circumstances, we conducted two research studies. In the first research, we presented a formulation of neutrosophic transport issues, and in the second research, we presented some ways to find a preliminary solution to these issues, but we do not know whether the preliminary solution is optimal or not, so we will present in this research a study whose purpose is to shed light on some important methods used to improve the optimal solution to transportation issues and then reformulating them using the concepts of neutrosophic science, a science that leaves nothing to chance or circumstances but rather provides solutions with neutrosophic values. Unspecified values take into account the best and worst conditions.

**Keywords:** Neutrosophic Science; Optimal Solution; Transportation; Stepping-Stone Method; Modified Distribution Method.

#### 1. Introduction

The linear programming method is one of the most important operations research methods that companies and institutions have benefited from in their workflows by building linear models for which science has provided ways to find the optimal solution. Given this importance, we have reformulated these models in two previous studies and found one of the most important ways to solve them using the concepts of neutrosophic science [1, 2]. The issue of transportation is one of the most important issues that have been dealt with using the linear programming method because transportation problems appear frequently in practical life. We need to transfer materials from production centers to consumption centers to secure the regions; we need the lowest possible cost, To solve these recurring and daily problems, we use operations research methods, specifically the linear programming method, where we transform the issue data into a classical linear mathematical model when the data are classical and neutrosophic model when the data are neutrosophic. And in the research [3], there is a full explanation of the neutrosophic transport issues. Since these models are linear neutrosophic, we can get an optimal solution by using the direct simplex neutrosophic method described in the research [1].

But we know that these models have special characteristics, in terms of restrictions and objective function, which enabled scientists and researchers to find special methods, the methods in which we get preliminary solutions, and we explained how to obtain a preliminary solution for the neutrosophic transport in the research [4], and we recall that the neutrosophic transport issues are

transport issues in which the required quantities and the available quantities are neutrosophic values of the form  $Na_i \in a_i + \varepsilon_i$ , where  $\varepsilon_i$  the indeterminacy of the produced quantities can take the forms  $\varepsilon_i \in [\lambda_{i1}, \lambda_{i2}]$ . In addition, the required quantities of neutrosophic values of the form  $Nb_j \in b_j + \delta_j$ , where  $\delta_j$  is the indeterminacy of the quantities produced we take it as one of the forms  $\delta_j \in [\mu_{j1}, \mu_{j2}]$ . and the cost of transportation is neutrosophic values form  $Nc_{ij} \in c_{ij} + \alpha_{ij}$ , where  $\alpha_{ij}$  is the indeterminacy of the cost of transportation, we take it as one of the form  $c_{2j} \in \{\alpha_{1_{2j}}\alpha_{2_{2j}}\}$ . In order to review the basic concepts of neutrosophic science and its stages of development and the most important topics of operations research that have been reformulated using the concepts of this science, the following research can be found [5-16].

#### 2. Methods

The purpose of this research, as we mentioned in the abstract, is to highlight some of the methods used according to classical logic to improve the preliminary solution to transportation issues, where we will present:

- i. The Stepping-Stone Method
- ii. Modified Distribution Method

As stated in some references [17-20], with a focus on the scientific basis on which these methods were based, and then we will reformulate them using the concepts of neutrosophic science and use them to improve the solution of neutrosophic models after finding a preliminary solution for them using one of the methods mentioned in the reference [4].

# 2.1 The Stepping-Stone Method

To reach the optimal solution in this way, we follow the following steps:

- i. We find the preliminary solution by one of the three aforementioned methods, then we calculate the total cost according to the preliminary solution.
- ii. We identify the basic variables from the non-basic variables from the preliminary solution table.
- iii. We determine the indirect cost by finding closed paths, as each closed path has its beginning and end as a non-basic variable and consists of horizontal and vertical lines whose pillars are basic variables, as it happens that there are two basic variables in the way of the path, so we deviate from the basic non-basic variable and in general, the closed path represents in the following Figure 1:

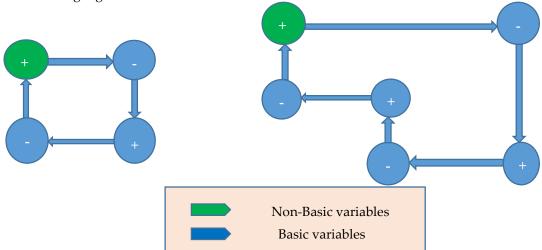


Figure 1. A representation of closed pathways.

We calculate the indirect cost of each non-basic variable by giving the cost of the non-basic variable a positive sign, and the cost of the basic variables we give it alternating negative and then positive signs, and so on. If the basic variables are positive or zero, this means that the solution that

we got is optimal and we stop. But if at least one of the indirect costs is negative, then we must develop the solution by choosing one of the non-basic variables to become basic and the exit of one of the basic variables.

#### Note:

To determine the basic internal variable, we take the non-basic variable that achieved the most negative in the indirect cost, and to make the solution the best possible, we try to pass in it the largest possible amount, we explain the above through the following example 1:

## Example 1:

The following Table 1 represents the cost of transporting goods from sources  $A_i$ ; i = 1, 2, 3, 4 to distribution centers  $B_j$ ; j = 1, 2, 3, 4 it is required to use the mobile quarantine method to improve the solution and obtain the ideal solution:

| Tuble 1. 1950c cata.                           |          |       |       |                         |  |  |
|--|----------|-------|-------|-------------------------|--|--|
| Consumption<br>center<br>Production<br>centers | $B_1$    | $B_2$ | $B_3$ | Available<br>Quantities |  |  |
| $A_1$  | 2        | 4     | 0     | 150                     |  |  |
| $A_2$  | {3, 4.5} | {1,2} | {5,8} | 200                     |  |  |
| $A_3$  | 6        | 2     | 4     | 325                     |  |  |
| $A_4$  | 1        | 7     | 9     | 25                      |  |  |
| Required quantities                            | 180      | 320   | 200   | 700                     |  |  |

Table 1. Issue data.

In this example, the cost of transportation of the product at the production center  $A_2$  is neutrosophic values we take in forms  $c_{2j} \in \left\{\alpha_{1_{2j}}\alpha_{2_{2j}}\right\}$ .

# The solution:

We find the initial solution using the least cost method; we get the following preliminary solution Table 2.

| , , , , , , , , , , , , , , , , , , , |          |              |          |                         |  |  |
|---------------------------------------|----------|--------------|----------|-------------------------|--|--|
| Consumption center Production centers | $B_1$    | $B_2$        | $B_3$    | Available<br>Quantities |  |  |
| $A_1$                                 | 2        | 4            | 0<br>150 | 150                     |  |  |
| $A_2$                                 | {3,4.5}  | {1,2}<br>200 | {5,8}    | 200                     |  |  |
| $A_3$                                 | 6<br>155 | 2<br>120     | 4<br>50  | 325<br>170<br>50        |  |  |
| $A_4$                                 | 1<br>25  | 7            | 9        | 25                      |  |  |
| Required                              | 180      | 320          | 200      | 700                     |  |  |
| quantities                            | 155      | 120          | 50       | 700                     |  |  |

Table 2. Preliminary solution.

We note that the number of occupied squares is equal to m + n - 1 = 6

The total transportation cost according to the preliminary solution is:

$$Z_1 = 0 \times 150 + \{1,2\} \times 200 + 6 \times 155 + 2 \times 120 + 4 \times 50 + 1 \times 25$$

For  $c_{22} = 1 \Rightarrow Z_1 = 1595$ 

For  $c_{22} = 2 \Rightarrow Z_1 = 1795$ 

That is, against this preliminary solution, we have a neutrosophic value for the total transportation cost:

$$Z_1 \in \{1595,1795\}$$

Now we see whether this solution is an optimal solution or not?

For this we define basic variables and non-basic variables, it is clear that

The basic variables are:

$$x_{13}$$
,  $x_{22}$ ,  $x_{31}$ ,  $x_{32}$ ,  $x_{33}$ ,  $x_{41}$ 

#### The non-basic variables are:

$$x_{11}, x_{12}, x_{21}, x_{23}, x_{42}, x_{43}$$

We have six basic variables and six non-basic variables, so we get six closed paths are formed it is in Figure 2:

*Note*: The non-basic variables are green.

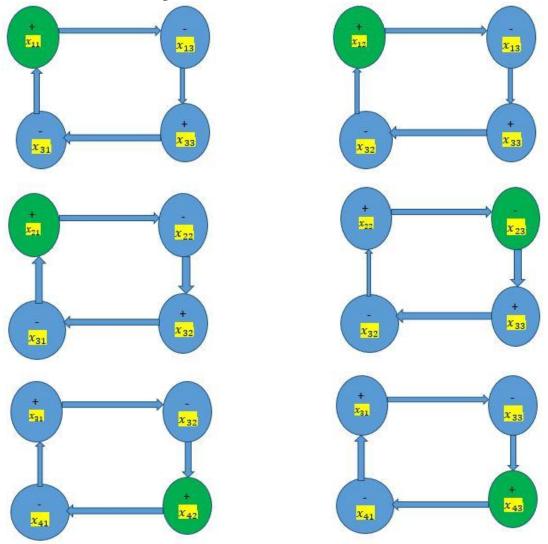


Figure 2. Possible closed paths after finding the initial solution.

The following Table 3, shows how the path is formed:

| Consumption center Production | B <sub>1</sub> | B <sub>2</sub> | $B_3$ | Available<br>Quantities |
|-------------------------------|----------------|----------------|-------|-------------------------|
| centers A <sub>1</sub>        | 2              | 4              | 0     | 150                     |
|                               |                | (1.5)          | 150   | 200                     |
| $A_2$                         | {3,4.5}        | {1,2}<br>200   | {5,8} | 200                     |
| $A_3$                         | 6              | 2              | 4     | 325                     |
|                               | 155            | 120            | 50    |                         |
| $A_4$                         | 1 25           | 7              | 9     | 25                      |
| Required quantities           | 180            | 320            | 200   | 700                     |

Table 3. Closed path identification.

We calculate the indirect cost, we find:

From the previous table and according to the drawn path, we explain how to calculate the indirect cost:

We start from the room  $(A_1B_1)$  we have the cost  $c_{11}=2$ , we take it with a positive sign because it is the room of the non-basic variable, then to the room  $(A_1B_3)$  we have the cost  $c_{13}=0$  We take here the minus sign and the variable in this room is a basic variable then to the room  $(A_3B_3)$  we have the cost  $c_{33}=4$ , we take here the sign is positive, and the variable in this room is a basic variable then to the room  $(A_3B_1)$  we have the cost  $c_{31}=6$  We take here the minus sign, and the variable in this room is a basic variable, So the indirect cost of the non-essential variable is  $x_{11}$  is:

$$x_{11}$$
: 2 - 0 + 4 - 6 = 0

In the same way, we calculate the cost for all non-essential variables we find:

$$x_{12}: 4-0+4-2=6$$

$$x_{21}: \{3,4.5\} - \{1,2\} + 2-6 = \{-2,-3,-0.5,-1,5\}$$

$$x_{23}: \{5,8\} - 4+2-\{1,2\} = \{2,1,5,4\}$$

$$x_{42}: 7-1+6-2=10$$

$$x_{43}: 9-1+6-4=10$$

We note that the indirect cost corresponding to the basic variable  $x_{21}$  is a negative amount and it is the only one, so we enter this variable and it becomes one of the basic variables and we exit instead of  $x_{31}$ 

We notice that we can pass the quantity  $x_{21} = 155$ , then it becomes:

$$x_{31} = 0$$
,  $x_{32} = 275$ ,  $x_{22} = 45$ 

We get the following Table 4:

| Consumption center Production centers | $B_1$           | $B_2$       | $B_3$   | Available<br>Quantities |
|---------------------------------------|-----------------|-------------|---------|-------------------------|
| $A_1$                                 | 2               | 4           | 0 150   | 150                     |
| $A_2$                                 | {3, 4.5}<br>155 | {1,2}<br>45 | {5,8}   | 200                     |
| $A_3$                                 | 6               | 2 275       | 4<br>50 | 325                     |
| $A_4$                                 | 1 25            | 7           | 9       | 25                      |
| Required<br>quantities                | 180             | 320         | 200     | 700                     |

**Table 4**. The first improvement.

We note that the transportation cost is according to the previous solution:

$$Z_2 \in (0 \times 150 + \{3,4.5\} \times 155 + \{1,2\} \times 45 + 2 \times 275 + 4 \times 50 + 1 \times 25)$$

For 
$$c_{21} = 3$$
 and  $c_{22} = 1 \Rightarrow Z_2 = 1285$ 

For 
$$c_{21} = 3$$
 and  $c_{22} = 2 \Rightarrow Z_2 = 1330$ 

For 
$$c_{21} = 4.5$$
 and  $c_{22} = 1 \Rightarrow Z_2 = 1517.5$ 

For 
$$c_{21} = 4.5$$
 and  $c_{22} = 2 \Rightarrow Z_2 = 1562.5$ 

Therefore:

$$Z_2 \in \{1285, 1330, 1517.5, 1562.5\}$$

$$\forall \ Z_2 \in \{1285 \ , 1330 \ , 1517.5 \ , 1562.5 \ \} \Longrightarrow Z_2 < Z_1 \in \{1595, 1795\}$$

That is, this solution is better than the previous one, the question now is whether this solution is the optimal solution, for this we define the basic variables and the non-basic variables we find:

The basic variables are:

$$x_{41}$$
,  $x_{33}$ ,  $x_{32}$ ,  $x_{22}$ ,  $x_{21}$ ,  $x_{13}$ 

The non-basic variables are:

$$x_{43}$$
,  $x_{42}$ ,  $x_{31}$ ,  $x_{23}$ ,  $x_{12}$ ,  $x_{11}$ 

We have six basic variables and six non-basic variables, so we get six closed paths; we form the closed paths for the six non-basic variables in Figure 3:

Note: The non-basic variables are green.

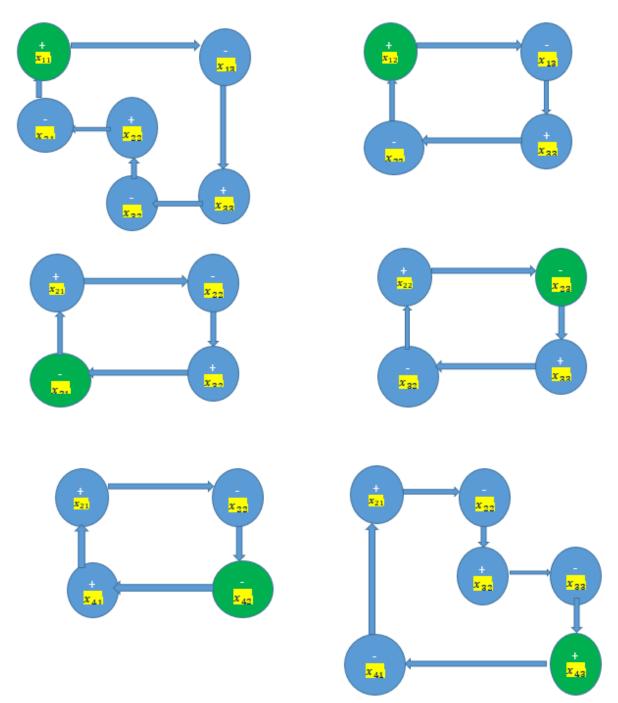


Figure 3. Possible closed paths after the first optimization.

We calculate the indirect cost:

$$x_{11}: 2-0+4-\{1,2\}+1-3=\{3,2\}$$

$$x_{12}: 4-0+4-2=8$$

$$x_{32}: 6-2+\{1,2\}-\{3,4.5\}=\{2,0.5,3,1.5\}$$

$$x_{42}: 7-\{1,2\}+\{3,4.5\}-1=\{8,9.5,7,8.5\}$$

$$x_{43}: 9-4+2-\{1,2\}+\{3,4.5\}-1=\{8,9.5,7,8.5\}$$

We note that the indirect cost for each non-basic variable is positive, and therefore we cannot introduce any non-basic variable to the basic rule. Therefore, the solution that we obtained in the first

improvement is an optimal vinegar, and the minimum transportation cost is the one that we obtained previously:

Therefore the optimal solution is:

$$x_{13} = 150$$
 ,  $x_{21} = 155$  ,  $x_{22} = 45$  ,  $x_{32} = 275$  ,  $x_{33} = 50$  ,  $x_{41} = 25$ 

The minimum cost of transportation is:

$$Z_2 \in \{1285, 1330, 1517.5, 1562.5\}$$

## 2.2 Modified Distribution Method

This method is another method of finding the optimal solution for transportation issues, and it is also similar to the previous method (the mobile stone method) conjunction.

To find the optimal solution to the transportation issue according to this method, we follow the following steps:

- i. We find the initial solution in one of the previously mentioned ways
- ii. We define the essential variables and non-basic variables for the solution
- iii. We associate with each line i multiplied by  $u_i$ , and with each column j multiplied, we call it  $v_j$ , so it is:

For each basic variable  $x_{ij}$  we have:

$$u_i + v_j = c_{ij} \tag{*}$$

Where  $c_{ij}$  is the cost from  $A_i$  to  $B_j$ :

Since the number of basic variables is m + n - 1, we get the m + n - 1 equation from the previous Figure (\*) and by solving these equations we must find the values of  $u_i$ ,  $v_j$  which have m + n so we must give one of these multipliers an optional value, then we solve these equations according to this value.

After we found the values  $u_i$ ,  $v_j$ , for each non-basic variable  $x_{ij}$  we calculate the quantities  $c_q = c_{ij} - u_i - v_j$ 

In a similar way to the moving stone method, but if one of these quantities is negative, then we must introduce a non-basic variable to the set of basic variables and output instead of a basic variable, and the primary variable entered is chosen in the same previous way:

#### Example 2:

Let's take the previous example, where we found the preliminary solution according to the cost method:

Consumption Available  $v_1$  $v_2$  $v_3$ center Quantities Production centers  $B_2$  $B_3$  $B_1$ 0 2 4 150  $A_1$  $u_1$ 150  $A_2$ {5,8} 200 {3,4.5} {1,2}  $u_2$ 200 6 2 4 325  $A_3$  $u_3$ 155 120 50 1 7 9 25  $A_4$  $u_4$ 25 Required 180 320 200 700 700 quantities

Table 5. The preliminary solution.

Transportation cost is:  $Z_1 = 1595$ 

Basic variables:

$$x_{13}, x_{22}, x_{31}, x_{32}, x_{33}, x_{41}$$

Non-basic variables:

$$x_{11}, x_{12}, x_{21}, x_{23}, x_{42}, x_{43}$$

Multipliers is:  $u_i$ ; i = 1,2,3,4 and  $v_j$ ; j = 1,2,3.

For basic variables, we have:

For  $x_{13}$ , we have  $u_1 + v_3 = 0$ 

For  $x_{22}$  we have  $u_2 + v_2 = \{1,2\}$ 

For  $x_{31}$ , we have  $u_3 + v_1 = 6$ 

For  $x_{32}$ , we have  $u_3 + v_2 = 2$ 

For  $x_{33}$ , we have  $u_3 + v_3 = 4$ 

For  $x_{41}$ , we have  $u_4 + v_1 = 1$ 

It is six equations with seven unknowns. To solve them, we impose  $u_1 = 0$ , so we find the rest of the variables:

$$u_1=0$$
 ,  $u_2=3$  ,  $u_3=4$  ,  $u_4=-1$  
$$v_1=2$$
 ,  $v_2=-2$  ,  $v_3=0$ 

For non-basic variables, we have:

$$x_{11}, x_{12}, x_{21}, x_{23}, x_{42}, x_{43}$$

For 
$$x_{11}$$
 it is:  $\bar{c}_{11} = c_{11} - u_1 - v_1 = 2 - 0 - 2 = 0$ 

For 
$$x_{12}$$
 it is:  $\bar{c}_{12} = c_{12} - u_1 - v_2 = 4 - 0 + 2 = 6$ 

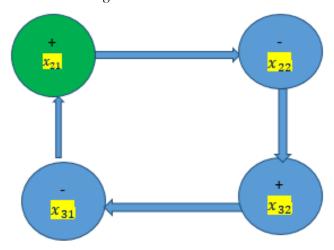
For 
$$x_{21}$$
 it is:  $\bar{c}_{21} = c_{21} - u_2 - v_1 = \{3,4.5\} - 3 - 2 = \{-2,-3.5\}$ 

For 
$$x_{23}$$
 it is:  $\bar{c}_{23} = c_{23} - u_2 - v_3 = \{5,8\} - 3 - 0 = \{2,5\}$ 

For 
$$x_{42}$$
 it is:  $\bar{c}_{42} = c_{42} - u_4 - v_2 = 7 + 1 + 2 = 10$ 

For 
$$x_{43}$$
 it is:  $\bar{c}_{43} = c_{43} - u_4 - v_3 = 9 + 1 - 0 = 10$ 

We note that the quantity  $\bar{c}_{21} = -2$  is a negative value, and therefore the initial solution that we got is not optimal, we must develop this solution, and for that, we form the closed path for the non-basic variable  $x_{21}$ , so we find it from the Figure 4:



**Figure 4**. Possible closed pathways for the non-basic variable  $x_{21}$ .

We enter  $x_{21}$  into the set of basic variables, by giving it the value  $x_{21} = 155$ , and we remove the variable  $x_{31}$  so it becomes a non-basic variable, and then it becomes  $x_{22} = 45$  and  $x_{32} = 275$ , so we get the following Table 6:

| Table 0. The mist improvement. |                        |         |       |     |       |     |            |     |
|--------------------------------|------------------------|---------|-------|-----|-------|-----|------------|-----|
|                                | Consumption center     | $v_1$   | $v_2$ |     | $v_3$ |     | Available  | ē   |
| Prod                           | uction centers         | $B_1$   | $B_2$ |     | $B_3$ |     | quantities | s   |
|                                | $A_1$                  | 2       | 4     |     | 0     |     | 150        |     |
| $u_1$                          |                        |         |       |     |       | 150 |            |     |
|                                | $A_2$                  | {3,4.5} | {1,2} |     | {5,8} |     | 200        |     |
| $u_2$                          |                        | 15      | 5     | 45  |       |     |            |     |
|                                | $A_3$                  | 6       | 2     |     | 4     |     | 325        |     |
| $u_3$                          |                        |         |       | 275 |       | 50  |            |     |
| $u_4$                          | $A_4$                  | 1 2     | 7     |     | 9     |     | 25         |     |
|                                | Required<br>quantities | 180     | 320   |     | 200   |     | 700        | 700 |
| -                              | •                      |         |       |     |       |     |            |     |

**Table 6.** The first improvement.

We enter  $x_{21}$  into the set of basic variables, by giving it the value  $x_{21} = 155$ , and we remove the variable  $x_{31}$  so it becomes a non-basic variable, and then it becomes  $x_{22} = 45$  and  $x_{32} = 275$ , so we get the following Table 6:

The new transfer cost is:

$$Z_2 \in \{1285, 1330, 1517.5, 1562.5\}$$

$$\forall Z_2 \in \{1285, 1330, 1517.5, 1562.5\} \Rightarrow Z_2 < Z_1 \in \{1595, 1795\}$$

This solution is better than the previous solution, but is it the optimal solution?

For basic variables, we have:

For  $x_{13}$  we have  $u_1 + v_3 = 0$ 

For  $x_{21}$  we have  $u_2 + v_1 = 3$ 

For  $x_{22}$  we have  $u_2 + v_2 = 1$ 

For  $x_{32}$  we have  $u_3 + v_2 = 2$ 

For  $x_{33}$  we have  $u_3 + v_3 = 4$ 

For  $x_{41}$  we have  $u_4 + v_1 = 1$ 

We assume  $u_1 = 0$  and solve the system of equations we find:

$$u_1 = 0$$
,  $u_2 = 3$ ,  $u_3 = 4$ ,  $u_4 = 1$   
 $v_3 = 0$ ,  $v_2 = -2$ , ,  $v_1 = 0$ ,

For non-basic variables:

For  $x_{11}$  it is:  $\bar{c}_{11} = c_{11} - u_1 - v_1 = 2 - 0 - 0 = 2$ 

For 
$$x_{12}$$
 it is:  $\bar{c}_{12} = c_{12} - u_1 - v_2 = 4 - 0 + 2 = 6$ 

For 
$$x_{21}$$
 it is:  $\bar{c}_{21} = c_{21} - u_2 - v_1 = \{3,4.5\} - 3 + 0 = \{0,1.5\}$ 

For 
$$x_{23}$$
 it is:  $\bar{c}_{23} = c_{23} - u_2 - v_3 = \{5,8\} - 3 + 0 = \{2,5\}$ 

For 
$$x_{42}$$
 then:  $\bar{c}_{42} = c_{42} - u_4 - v_2 = 7 - 1 + 2 = 8$ 

For 
$$x_{43}$$
 it is:  $\bar{c}_{43} = c_{43} - u_4 - v_3 = 9 - 1 - 0 = 8$ 

We note that all quantities  $\bar{c}_{ij}$  are positive quantities, so the solution that we got is optimal, and the minimum cost of transportation is:

$$Z_2 \in \{1285, 1330, 1517.5, 1562.5\}$$

$$\forall \ Z_2 \in \{1285 \ , 1330 \ , 1517.5 \ , 1562.5 \ \} \Longrightarrow Z_2 < Z_1 \in \{1595, 1795\}$$

Therefor the optimal solution is:

$$x_{13} = 150$$
 ,  $x_{21} = 155$  ,  $x_{22} = 45$  ,  $x_{32} = 275$  ,  $x_{33} = 50$  ,  $x_{41} = 25$ 

The minimum cost of transportation is:

 $Z_2 \in \{1285, 1330, 1517.5, 1562.5\}$ 

#### 3. Conclusion

In many practical issues, we encounter cases in which we are unable to provide confirmed data on the reality of the state of the system under study; the data is affected by circumstances surrounding the working environment, and this matter affects the future and may cause large losses. In the example that was presented in this research, we noticed the study gave us a neutrosophic transport cost suitable for all conditions because it was obtained through neutrosophic data.

## Acknowledgments

The author is grateful to the editorial and reviewers, as well as the correspondent author, who offered assistance in the form of advice, assessment, and checking during the study period.

# Data availability

The datasets generated during and/or analyzed during the current study are not publicly available due to the privacy-preserving nature of the data but are available from the corresponding author upon reasonable request.

#### **Conflict of interest**

The authors declare that there is no conflict of interest in the research.

## **Ethical approval**

This article does not contain any studies with human participants or animals performed by any of the authors.

## References

- Maissam Jdid, AA Salama, Huda E Khalid , Neutrosophic Handling of the Simplex Direct Algorithm to Define the Optimal Solution in Linear Programming , International Journal of Neutrosophic Science, Vol.18, No. 1, 2022
- 2. Maissam Jdid, Huda E Khalid, Mysterious Neutrosophic Linear Models, International Journal of Neutrosophic Science, Vol.18, No. 2, 2022
- 3. Maissam Jdid, Huda E. Khalid, Neutrosophic Mathematical formulas of Transportation Problems, Neutrosophic sets and Systems, NSS, Vol. 51,2022
- 4. Maissam Jdid, Huda E Khalid, An Investigation in the Initial Solution for Neutrosophic Transportation Problems (NTP), Neutrosophic sets and Systems NSS, Vol.50,2022
- 5. Florentin Smarandache, Maissam Jdid, On Overview of Neutrosophic and Plithogenic Theories and Applications, Applied Mathematics and Data Analysis, Vo. 2, No. 1, 2023
- 6. Maissam Jdid, Neutrosophic Nonlinear Models, Journal Prospects for Applied Mathematics and Data Analysis, Vo .2, No .1, 2023
- 7. Florentin Smarandache, Victor Christianto, A few little steps beyond Knuth's Boolean Logic Table with Neutrosophic Logic: A Paradigm Shift in Uncertain Computation, Vol 2, No 2, 2023
- 8. Aslam, M. (2019). Control Chart for Variance using Repetitive Sampling under Neutrosophic Statistical Interval System, IEEE Access, 7 (1), 25253-25262.
- 9. Maissam Jdid, Neutrosophic Mathematical Model of Product Mixture Problem Using Binary Integer Mutant, Journal of Neutrosophic and Fuzzy Systems (JNFS), Vo .6, No .2, 2023
- 10. Maissam Jdid, Florentin Smarandache, Said Broumi, Inspection Assignment Form for Product Quality Control, Journal of Neutrosophic Systems with Applications, Vol. 1, 2023

- 11. Maissam Jdid, Said Broumi, Neutrosophic Rejection and Acceptance Method for the Generation of Random Variables, Neutrosophic Sets and Systems, NSS, Vol.56,2023
- 12. Maissam Jdid, Florentin Smarandache, The Use of Neutrosophic Methods of Operation Research in the Management of Corporate Work, Journal of Neutrosophic Systems with Applications, Vol. 3, 2023
- 13. Maissam Jdid, Florentin Smarandache, Lagrange Multipliers and Neutrosophic Nonlinear Programming Problems Constrained by Equality Constraints, Journal of Neutrosophic Systems with Applications, Vol. 6, 2023
- 14. Maissam Jdid, Florentin Smarandache, Neutrosophic Treatment of Duality Linear Models and the Binary Simplex Algorithm, Applied Mathematics and Data Analysis, Vo .2, No .2, 2023
- 15. Maissam Jdid, Florentin Smarandache, Neutrosophic Treatment of the Modified Simplex Algorithm to find the Optimal Solution for Linear Models, International Journal of Neutrosophic Science (IJNS), Vol. 23, No.1,2023
- 16. Maissam Jdid, NEUTROSOPHIC TRANSPORT AND ASSIGNMENT ISSUES, Publisher: Global Knowledge's: 978\_1 \_59973\_770\_6, (Arabic version).
- 17. Al Hamid. Mohammed Dabbas, Mathematical programming, Aleppo University, Syria, 2010. (Arabic version).
- 18. Bukajah J.S., Mualla, W... and others Operations Research Book translated into Arabic The Arab Center for Arabization, Translation, Authoring and Publishing -Damascus -1998. (Arabic version).
- 19. Alali. Ibrahim Muhammad, Operations Research. Tishreen University Publications, 2004. (Arabic version)
- 20. Maissam Jdid, Operations Research, Published in ASPU, faculty of Information Technology, 2021.

Received: 19 Jul 2023, Revised: 12 Oct 2023,

Accepted: 15 Nov 2023, Available online: 04 Dec 2023.

