

# Brain Tumor Segmentation using hybrid of both Netrosopic Modified Nonlocal Fuzzy C-mean and Modified Level sets

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*Abstract: an improved segmentation approach based on Neutrosophic sets (NS) and Modified Non local Fuzzy c-mean clustering (NLFCM) is proposed. The brain tumor MRI image is transformed into NS domain, which is described using three subsets namely; the percentage of truth in a subset T%, the percentage of indeterminacy in a subset I%, and the percentage of falsity in a subset F%. The entropy in NS is defined and employed to evaluate the indeterminacy. NS image is adapted also using Modified Non local Fuzzy C-mean algorithm(MNLFCM). Finally, MRI brain tumor image is segmented and tumor is selected using Modified Level Sets (MLS). The proposed approach denoted as NS- MNLFCM-MLS and compared with another paper using Jaccard Index and Dice Coefficient.The experimental results demonstrate that the proposed approach is less sensitive to noise and performs better on MRI brain image.*

**Keywords:** Magnetic resonance imaging, Netrosophic, Nonlocal fuzzy c mean, Directional -mean operation ,modified level sets

## 1. Introduction

The Brain tumor segmentation methods can become classified into three classes in line with the level of required human being interaction as described simply by Foo et al. [1], Olabarriga et al. [2], and Yao [3]: manual segmentation, semiautomatic segmentation, and totally programmed segmentation. Brain tumors are hard to segment since they have a variety of presence and effect on adjoining structures. Following are several of the typical characteristics of brain tumors: (A) change greatly in dimensions and placement, (B) vary greatly in the way they be present in MRI, (C) might have overlapping intensities with normal tissue, (D) can be space occupying (new tissues that moves normal structure) or infiltrating (changing real estate of existing tissue), (E) may enhance fully, somewhat, or not at every, with contrast agent.

Clustering is known as a generally used mathematical procedure which in turn performs segmentation process to distinguish the structures and maternity shapes present in a great input image or dataset [4] It could be categorized into two groups: hierarchical and dividing [5].The output of hierarchical clustering are like tree and they don't need to specify the number of the amount of the clusters and independent of the first condition. However, it might fail to separate overlapping clusters due to not enough information regarding the size of clusters or its global condition. Dividing clustering algorithm on fix the disadvantage of hierarchical clustering algorithm partitions the data set in to specific number of groupings. Fuzzy based clustering allows partition

an input photo into several homogenous classes or clusters, by which in turn identical conditions are grouped found in a same class and non-identical items belong to different classes.

The majority of the algorithms found in image processing are susceptible to several uncertainties, pertaining to instance, grayness ambiguity (uncertainty inside the input details itself). The key aim of this work should be to lessen uncertainty while clustering .Generally there are two main tactics in clustering technique particularly crisp and fuzzy clustering technique. Due to different situations, for images, problems like small scale of spatial resolution, poor light, occurrence of noise, power imbrications leads crisp segmentation a hard task.Between numerous clustering techniques, fuzzy c-means (FCM) [6] algorithm is usually more significant as a result of the robustness.

Although it is definitely robust it works just on the images with no noise. Many researchers experience analyzed brain MRI segmentation using FSs, see Zhao [7] Agrawal [8]. Yet these algorithms still include problems due to different situations, for instance, taking brain images under low of the illumination make it unclear. In general, FCM criteria have greater data managing capacity and have better operability after diversified info range. Due to the application of pixel neighborhood information, RFCM algorithm has nice overall performance of noise restraining, and gets good segmentation benefits comparing with standard FCM. Yet, we found that with all the increase of normal deviation of noise, the ability of noise reductions of FCM algorithm might become weaken. V. P. Ananthi [9] use Segmentation of brain tumor based on

interval- respected intunistic fuzzy sets features Dice coefficient equal zero. 967. M. Zarinbal [10] work in astrocytomas extraction only using type 2 fuzzy and have got accuracy of 89%.

In respect to this situation, all of us put forward clustering algorithm based in non-local information NON-LOCAL unclar C-means clustering, (NL FCM), a greater weighted neighborhood details can be used, so it is definitely better to suppress sounds than that of RFCM algorithm. Non-local regularization was first formerly used for picture denoising, called non-local indicate denoising [11]. The algorithm essentially uses the redundant information of normal structure, frankly neighborhood about a pixel and as well other neighbor pixels found in the same scene may match with each various other. The NLFCM algorithm identifies a weighted graph of all pixels in the image, in which the weight value is received by similarity calculation of two neighborhood pixels

The convergence rate gets affected if the number of clusters and iterations are subsequently increased. Diminishing the number of iterations and clusters to obtain faster convergence rate has an adverse effect upon the segmentation accuracy . To overcome these kinds of hindrances, a novel segmentation algorithm which combines Neutrosophy studies the foundation, characteristics, scope of neutralities, and their interactions with distinct ideational spectra. It is usually a new philosophy that extends fuzzy logic and is the basis of neutrosophic logic, neutrosophic likelihood, neutrosophic set theory, and neutrosophic statistics. Because the world is filled with indeterminacy, the imperfection of understanding that a human receives/observes from the external universe also causes imprecision. Neutrosophy introduces a new principle <Neut-A>, which is definitely the representation of indeterminacy. However, this theory can be mostly discussed in physiology and mathematics. Thus, applications to prove this theory can resolve real challenges are needed. In this kind of dissertation, I apply neutrosophy to brain tumor segmentation. In brain tumor segmentation, neutrosophy helps reduce noises. In MRI brain tumour segmentation, neutrosophy integrates two controversial opinions about noise.

## 2. Proposed algorithm

An superior segmentation approach based upon Neutrosophic sets (NS) and Non local Fuzzy c-mean clustering (NLFCM) is recommended. The brain tumor MRI image is become NS domain, which is defined using three subsets particularly. The entropy in NS is defined and employed to gauge the indeterminacy. NS image is modified using Moving Mean Operation (MMO) and also using Modified Not local Fuzzy C-mean algorithm (MNLFCM) Finally, MRI brain growth image is segmented and tumor selected applying Modified Level Sets (MLS).The propose approach denoted as NS- MNLFCM-MLS and usir Maxima Morphological Transform (MMT) to find accurate tumor boundary. We compared with another newspaper using

sensitivity , Specificity and Dice Coefficient. The trial and error results demonstrate the fact that offered approach is less hypersensitive to noise and functions better on MRI brain image. Figure 1 show the flowchart of the proposed approach.

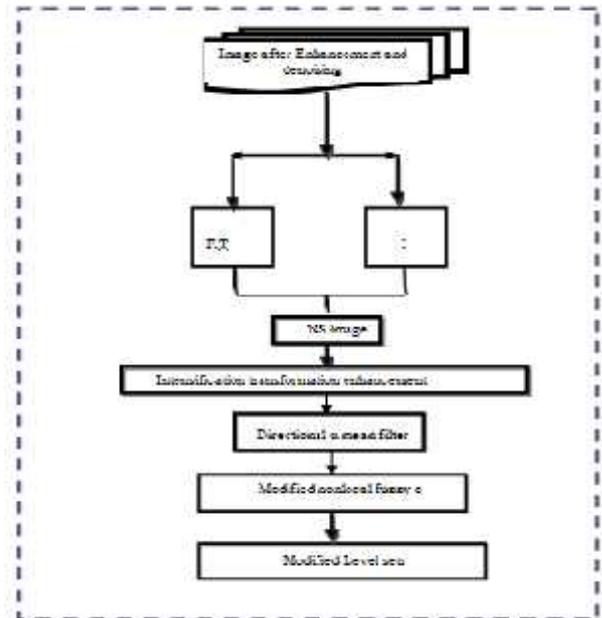


Fig 1: Step of Proposed Algorithm

### 2.1 Neutrosophic MRI brain tumor Image

Let  $U$  get an universe of talk, and  $W$  be a set included in Circumstance, which is composed simply by bright pixels. A neutrosophic image  $P$  is indicated by three subset  $T$ ,  $I$  and  $F$ . A pixel  $P$  in the image is identified as  $P(T, My\ spouse\ and\ i, F)$  and belongs to  $W$  in the next way: it is  $t\%$  true in the dazzling pixel set,  $i\%$  indeterminate, and  $f\%$  bogus, where  $t$  varies in  $T$  varies  $I$ , and  $f$  varies in  $N$ . The pixel  $P(i, j)$  in the image website is transformed into neutrosophic domain  $P$   
 $NS(i, j) = T(i, j), I(i, j), F(i, j)$ . Where  $T(i, j)$ ,  $I(i, j)$  and  $F(i, j)$  will be the probabilities belong to bright white set, indeterminate set and non-white set, respectively [12], which are described as: equation below:

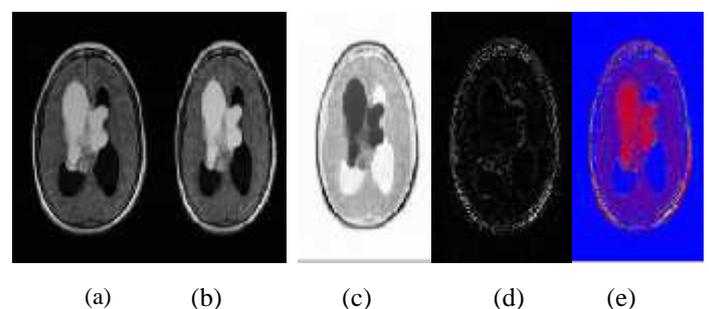


Fig 2:a) Input MRI image, b)True part. c)False part. d) Indeterminance part ,e) Neutrosopic MRIimage

The pixel  $P(i, j)$  in the image domain is transformed into Neutrosophic domain  $PN$

$S(i, j) = \{T(i, j), I(i, j), F(i, j)\}$ .  
 Where  $T(i, j)$ ,  $I(i, j)$  and  $F(i, j)$  are the probabilities belong to white set, indeterminate set and non-white set, respectively, which are defined in the following equations.

$$P_{NS}(i, j) = \{T(i, j), I(i, j), F(i, j)\} \quad (1)$$

$$H_o(i, j) = \text{abs}(g(i, j) - \overline{g(i, j)}) \quad (2)$$

$$F(i, j) = 1 - T(i, j) \quad (3)$$

$$\overline{g(i, j)} = \frac{1}{w \times w} \sum_{m=i-w/2}^{i+w/2} \sum_{n=j-w/2}^{j+w/2} g(m, n) \quad (4)$$

$$T(i, j) = \frac{\overline{g(i, j)} - \overline{g_{min}}}{\overline{g_{max}} - \overline{g_{min}}} g(m, n) \quad (5)$$

$$I(i, j) = 1 - \frac{H_o(i, j) - H_{o_{min}}}{H_{o_{max}} - H_{o_{min}}} \quad (6)$$

Where  $\overline{g(i, j)}$  is the local mean value of the image,  $H_o(i, j)$  is the homogeneity value of  $T$  at  $(i, j)$  which is described by the absolute value of difference between intensity  $g(i, j)$  and its local mean value  $\overline{g(i, j)}$ . Figure show input image and if of the enhanced MRI image then NS Image are shown in fig (D)

### 2.2 Enhancement of NS MRI brain tumor Image

The MRI brain tumor picture in NS domain might increased using intensification transformation enhancement technique (ITET) to increase the top quality and emphasizes certain features of a picture to makes segmentation easier and more effective [13]. Figure 3 show result of using (ITET)

$$E(T(x, y)) = 2T^2(x, y) \quad 0 < T(x, y) < 0.5 \quad (7)$$

$$E(T(x, y)) = 1 - 2(1 - T(x, y))^2 \quad 0.5 < T(x, y) < 1 \quad (8)$$

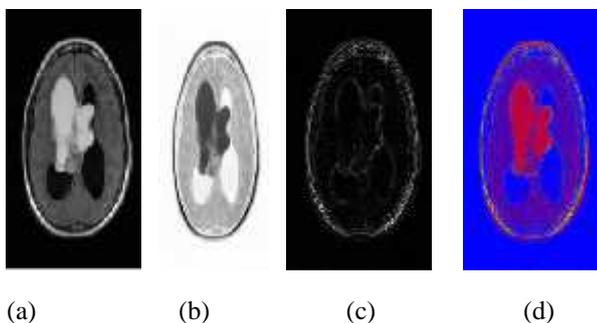


Fig 3: A) Enhanced True, b) Enhanced False. C) Enhanced Indetermination. d) Enhanced Neutrosophic Image.

### 2.3 Entropy of NS brain tumor MRI Image

Entropy is utilized to assess the distribution of diverse gray level in mind tumor MRI images. In the event that the

entropy is optimum, the several intensities have even probability and the features distribute uniformly. If the entropy is small, the intensities have different possibilities and their distributions are actually non-uniform.

Definition 1 (Neutrosophic image entropy) NS picture entropy is defined while the summation of the entropies of three subsection, subdivision, subgroup, subcategory, subclass F, T and I, which is employed to evaluate the distribution in the components in NS site [14]:

$$EnT = - \sum PT(i) \ln PT(i) \quad (9)$$

$$EnF = - \sum PF(i) \ln PF(i) \quad (10)$$

$$EnI = - \sum PI(i) \ln PI(i) \quad (11)$$

$$EnNS = EnT + EnI + EnF \quad (12)$$

Where  $EnI$ ,  $EnT$  and  $EnF$  are the entropy of subsets  $T$ ,  $I$  and  $F$ , respectively as shown in fig 4.



Fig4: GUI Result of entropy calculation

### 2.4 Directional -mean operation

In [14], an  $\alpha$ -mean functioning was defined on a neutrosophic image, and it taken off noise efficiently. However, it could blurring the image and lessen the contrast, which can reduce the performance of the segmentation to overcome this kind of drawback, directional  $\alpha$ -mean operation denoted as DAM is usually newly proposed to remove the noise effect and conserve the edges at the same time. The function of the directional mean filter DAM is identified as [16]:

$$DMF(i, j) = \begin{cases} R_1 & |G_m(i, j) - G_r(i, j)| \leq \sigma \\ R_2 & G_m(i, j) - G_r(i, j) > \sigma \\ R_3 & G_r(i, j) - G_m(i, j) > \sigma \end{cases} \quad (13)$$

Where  $G(i, j)$  Th and  $G(i, j)$  TV are the norm of the gradient at  $(i, j)$  at the horizontal and vertical direction, respectively.

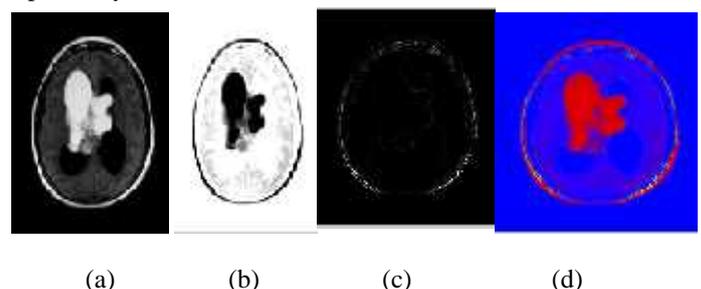


Fig 5 : Directional mean enhancement of :a)T,b)I,c)F,d)NS



## 2.6 Maxima transform Enhancement

For an graphic is definitely made using morphological operations such as iterated dilations of the image and later it is camouflaged. Koh et al [29] have defined H transform as where RI (I - h) is the retraced image by dilating I with respect to I - h. This sort of restrains all pixels in whose power rate is littler than the limit if maybe the worth is rather than their neighbors. Well then locate all territorial ideal of picture and individual the pixels of successive force. Maxima strategy is taken out utilizing the equation Regional maxima of H-maxima changed group picture having tumor can be utilized to uproot neighborhood pixels of power underneath h from the capabilities. Utilizing Eq. (9), last particular tumor locale is unquestionably separated without edema and other non-tumor area. H-maxima change happen to be shown in Fig.8.

$$H_{\max_h}(I) = R_I(I - h), \quad (20)$$

$$T_{\max_h}(I) = R_{\max}(H_{\max_h}(I)) \quad (21)$$

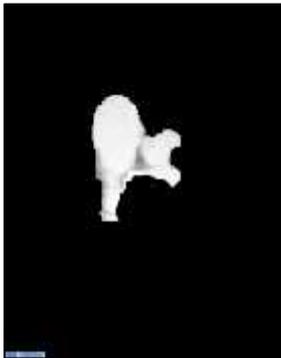


Fig 8: Segmented tumor using H transform

## 2.7 Performance Evaluation Metric:

The datasets for experimental analysis were obtained from Mansoura Hospital University MRI Scan. Tests are executed on numerous brain MR image datasets having tumor. To evaluate the segmentation accuracy, we used three metrics, namely, (i) the Dice Similarity Coefficient (DSC), (ii) the 98-percentile modified Hausdorff distance (H98)[30]. The following subsections will describe each used metric in more detail.

A) Dice Similarity Coefficient The Dice similarity coefficient (DSC) measures set agreement between two sets (S,G), and is defined as the union size of the two sets divided by the average size of the two sets

$$DSC(S, G) = (2|S \cap G| / (|S| + |G|)) \times 100 \quad (22)$$

In segmentation validation, the DSC is usually expressed in terms of false positive (FP), false negative (FN), true negative (TN), and true positive (TP) counts, which were obtained by comparing the segmentation results to the ground truth (gold standard) (see Figure 31). These values can be used to calculate the DSC as shown by [30]:

$$DSC = 2TP / (2TP + FP + FN) \times 100 \quad (23)$$

A DSC estimation of zero shows no cover; an estimation of one demonstrates perfect division. Higher numbers show better division, which implies that the division results coordinate the ground truth superior to anything results with lower qualities DSC values.

Table 1: Accuracy of the proposed segmentation approach for each subject using dice similarity coefficient (DSC(%)). &Accuracy of the proposed segmentation approach for each subject using the 98 percentile modified Hausdorff distance

Patient number	DSC	Hausdorff
p.1	98.403	2.05
P.2	96.56	5.13
p.3	97.34	1.78
p.4	96.76	12.43

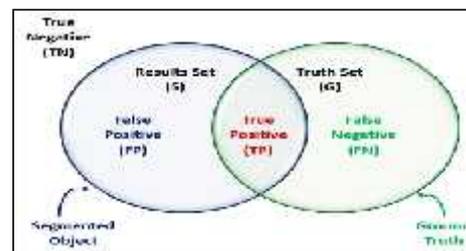


Fig 9: Diagram illustrating the meaning of segmentation errors, namely, true positive (TP), false positive (FP), true negative (TN), and false positive (FP). These segmentation errors, obtained by comparing the segmented and the ground truth objects, are used to calculate the dice similarity coefficient (DSC).

## B) Modified Hausdorff Distance

Distance measures are another type of performance metric used for evaluating segmentation methods. The Euclidean distance is often utilized, but another common measure is the Hausdorff distance (H). The H value from a set S to a set G is defined as the maximum distance of the set S to the nearest point in the set G (see Figure 6 [30]):

$$H(S, G) = \max_{s \in S} \{ \min_{g \in G} \{ d(s, g) \} \}, \quad (24)$$

where s and g are points of sets S and G, respectively, and d(s, g) is Euclidean distance between these points. The bidirectional Hausdorff distance, denoted by H (S, G), between the segmented region (S) and its ground truth (G) is defined as:

$$HBi(S, G) = \max \{ H(S, G), H(G, S) \}. \quad (25)$$

In this paper, to eliminate the effect of segmentation outliers, the 98-percentile modified Hausdorff distance (MH) was used to assess the proposed segmentation framework accuracy. Metrics were computed by comparing a ground truth segmentation to results from the proposed segmentation technique. The detailed segmentation results for each subject are given in Tables 1

As demonstrated in Table 1, the DSC for segmentation of the brain tumor is gives good result using our proposed algorithm .Performance shown in fig (9) and in table2.

**Conclusion:**

In this paper, the proposed full automatic brain tumor segmentation technique has been denoted as NS- MNLFCM-MLS and using Maxima Morphological Transform (MMT) to find accurate tumor boundary. It is based on neutrosophic preprocessing method and Modified non local fuzzy c mea Clustering method Compared with another new paper using Jaccard Index and Dice Coefficient. Results demonstrate the fact that offered approach is less hypersensitive to noise and functions better on MRI brain image .Proposed algorithm give high accuracy result compared with another methods. The results of the proposed method show that the 100% detection rate in all 34 cases with average of high dice 99.37%, high specificity 99. 26% and lower missing rate 0.52, and modified Hausdroff distance 1.302.

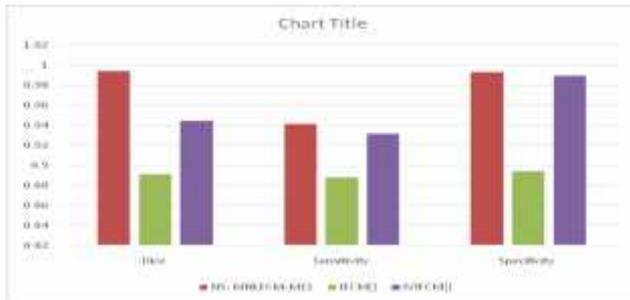


Fig9; Comparison of proposed algorithm and paper[9],[10]

Table 2: Accuracy of the proposed segmentation approach for each MRI brain tumor for 34 patient using dice ,sensitivity and specitivity &Accuracy of the proposed segmentation approach for each subject using the 98

	Dice	Sensitivity	Specificity
NS-MNLFCM-MLS	<b>0.9937</b>	<b>0.9412</b>	<b>0.9926</b>
IFCM[9]	<b>0.8908</b>	<b>0.8876</b>	<b>0.894</b>
IVIFCM[10]	0.9440	<b>0.9314</b>	<b>0.9892</b>

**Refereance**

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